My background:

Using small manned and unmanned aircraft for atmospheric research (meteorology, earth observation, both in-situ and remote sensing)

CYRIL HERTZ





The logos above are representing the network in which we are working:

- METAIR / ARA / Flinders since more than 30 years in the field of atmospheric research with small manned platforms
- COST-Action ES0802 (2008-2012) as a trigger for our first UAS "UMARS"
- SESAR-JU (member of the scientific committee) as a source of information about the integration of RPAS in Civil Aviation (SESAR is a several billion project of the EU, to establish the future ATM system in close coordination with EUROCONTROL and EASA (details see homepage)
- Important remark right at the beginning:
 Flying within line of sight, rather low (no formal limit in Switzerland), with "model aircraft" < 30 kg is not a big problem (even > 30 kg).
 But: With no direct visual contact, even for smaller objects, the legal situation is very strict. These are two "different worlds".

Flying low ...





FLYNET, ETHZ, Bruno Neininger 04.11.2014, Slide5

... and high up to 6 km altitude



Contraction of

Then we developed the UAS ZHAW-UMARS, flying a campaign in 2011.

Both UMARS_1 and UMARS_2 have wing spans of 5 m, MTOM of 30 kg, relatively high speed of 30 to 40 m/s, and an electrical endurance of more than one hour for fully autonomous operation (except T/O & LDG) or RPAS.





We flew manned and unmanned platforms combined (Aug 2011, for ETH)



Same flight pattern (funnel and cross section) from above



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There was even a third airborne system involved:



A tethered balloon from ETHZ (Prof. Dr. Nina Buchman et al.)



A new development we just have heared from (has nothing to do with ZHAW or METAIR, but, is showing that there is more activity on the topic – maybe closer to your applications):



http://www.meteomatics.com/en/inhalt/meteodrones/





Unmanned Aerial Systems in Atmospheric Research

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Links that might be interesting for you:

follow-up, since 2013: http://www.isarra.org/isarra2014.html

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Thank you!



(photo Marc Gerber, ZHAW)